

## Department of Computer Science and Engineering, HKUST RIScan: RIS-aided Multi-user Indoor Localization Using COTS Wi-Fi

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### Abstract and Background

The multi-user indoor localization system is very helpful in many daily scenarios. For instance, in museum, it can provide

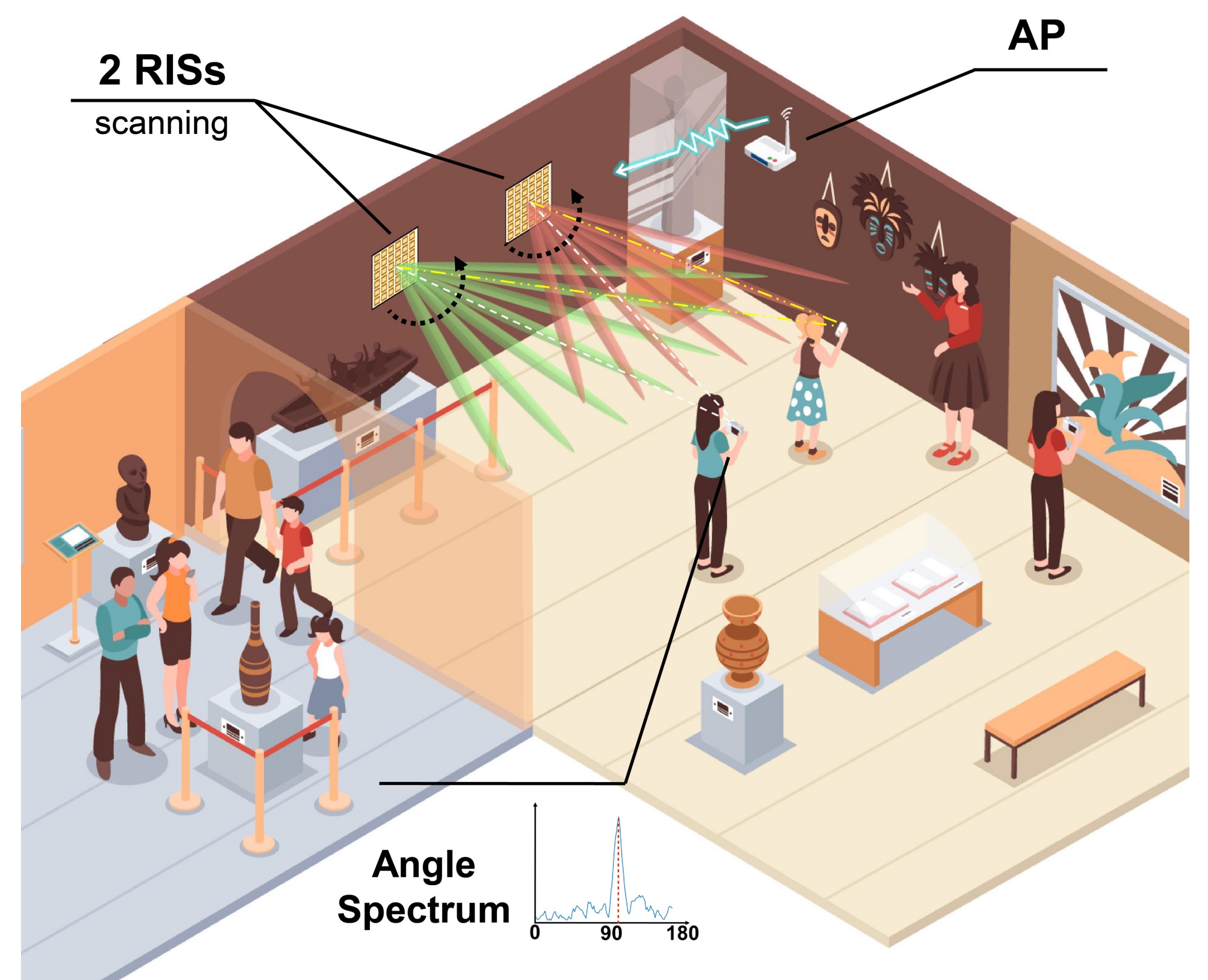
- **Indoor Navigation** help visitors quickly find the exhibits they are interested in
- **Smart interaction with showcases** automatically display the introduction of exhibits when they walk close

A practical multi-user localization system should meet the following two essential requirements which state-of-the-art systems cannot satisfy with at the same time

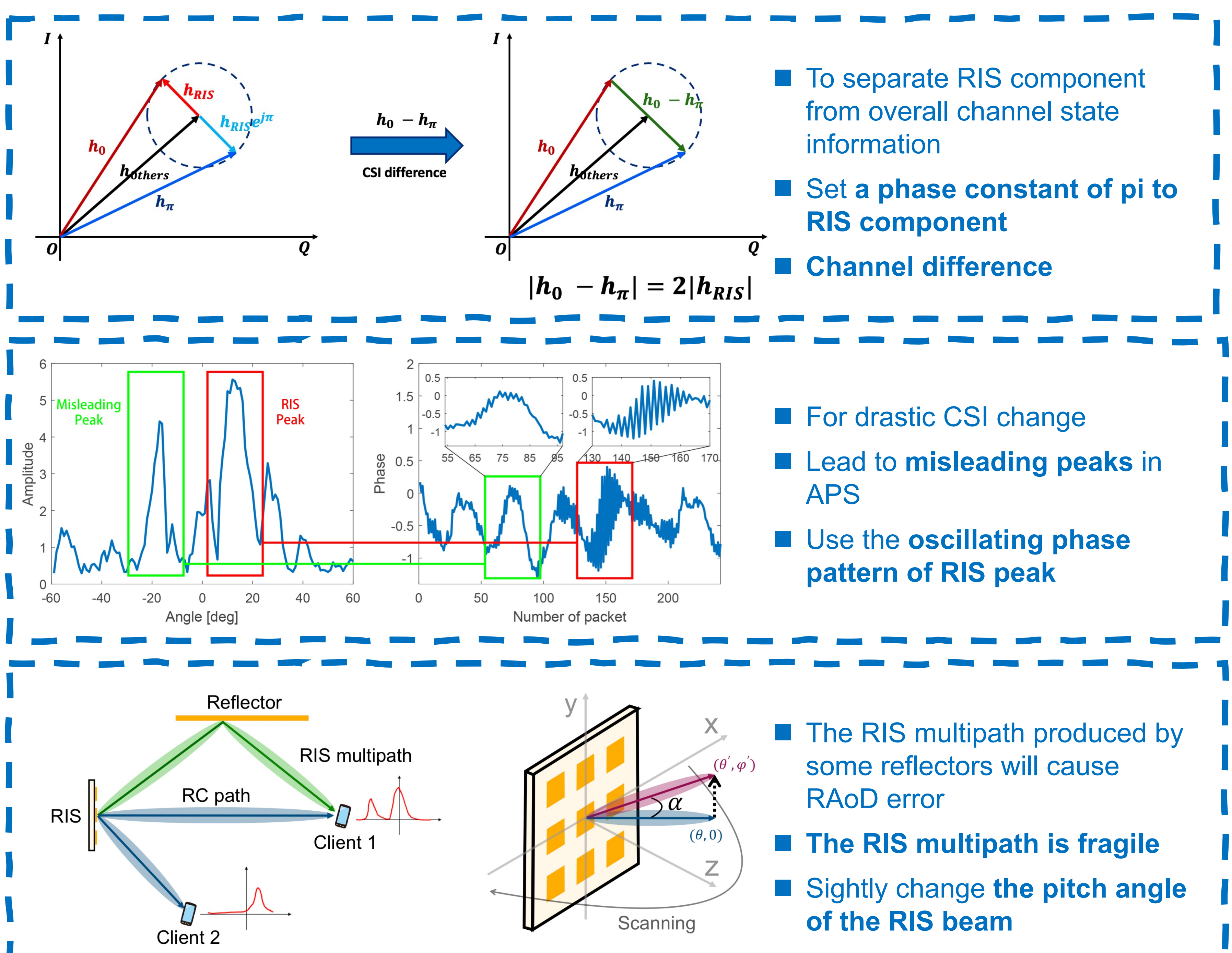
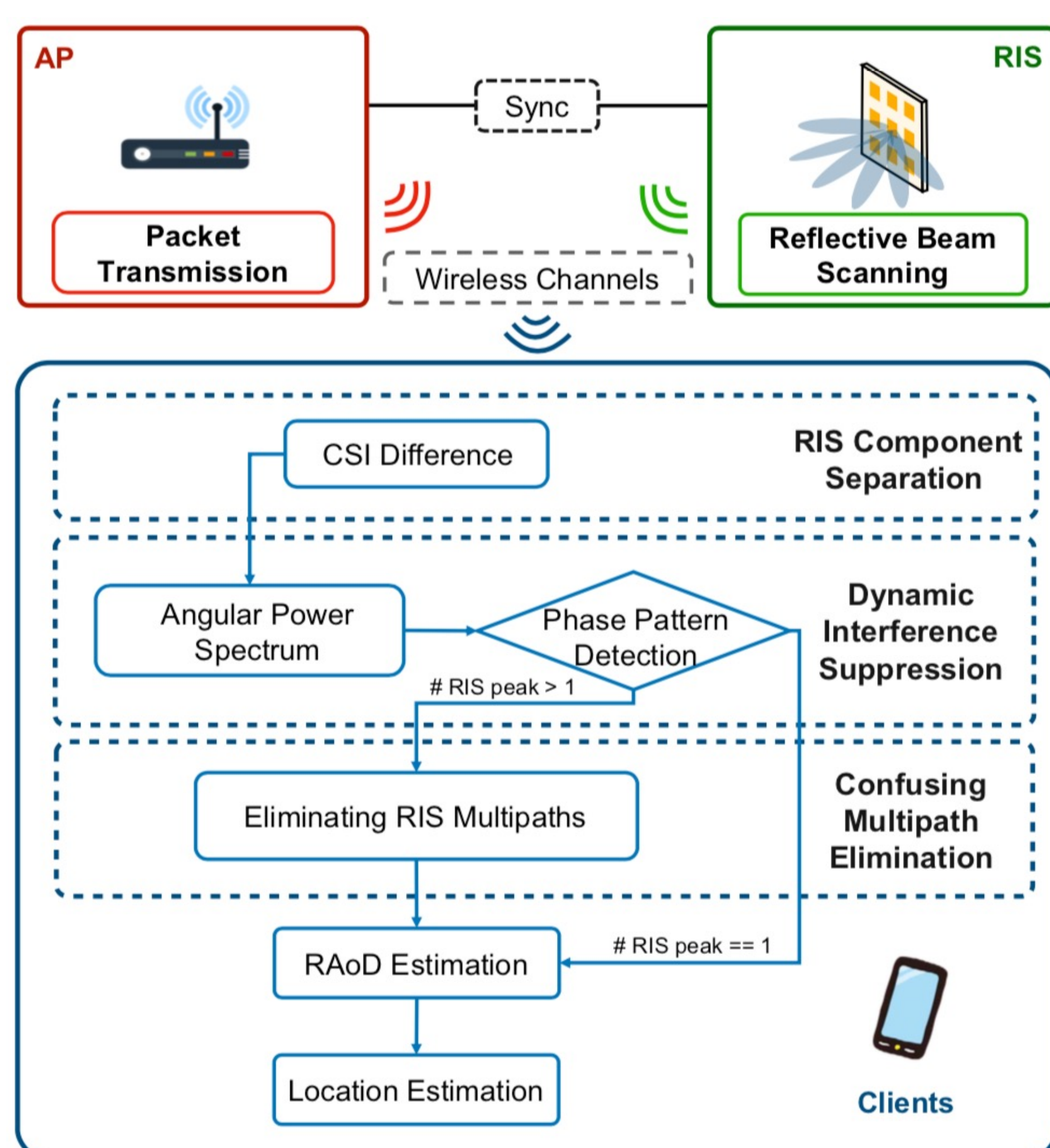
- **Low localization latency** for each client
- **High robustness** to dynamic interference from surrounding people

We propose RIScan, a parallel multi-user indoor localization system with a pair of Reconfigurable Intelligent Surfaces (RIS). We achieve it by

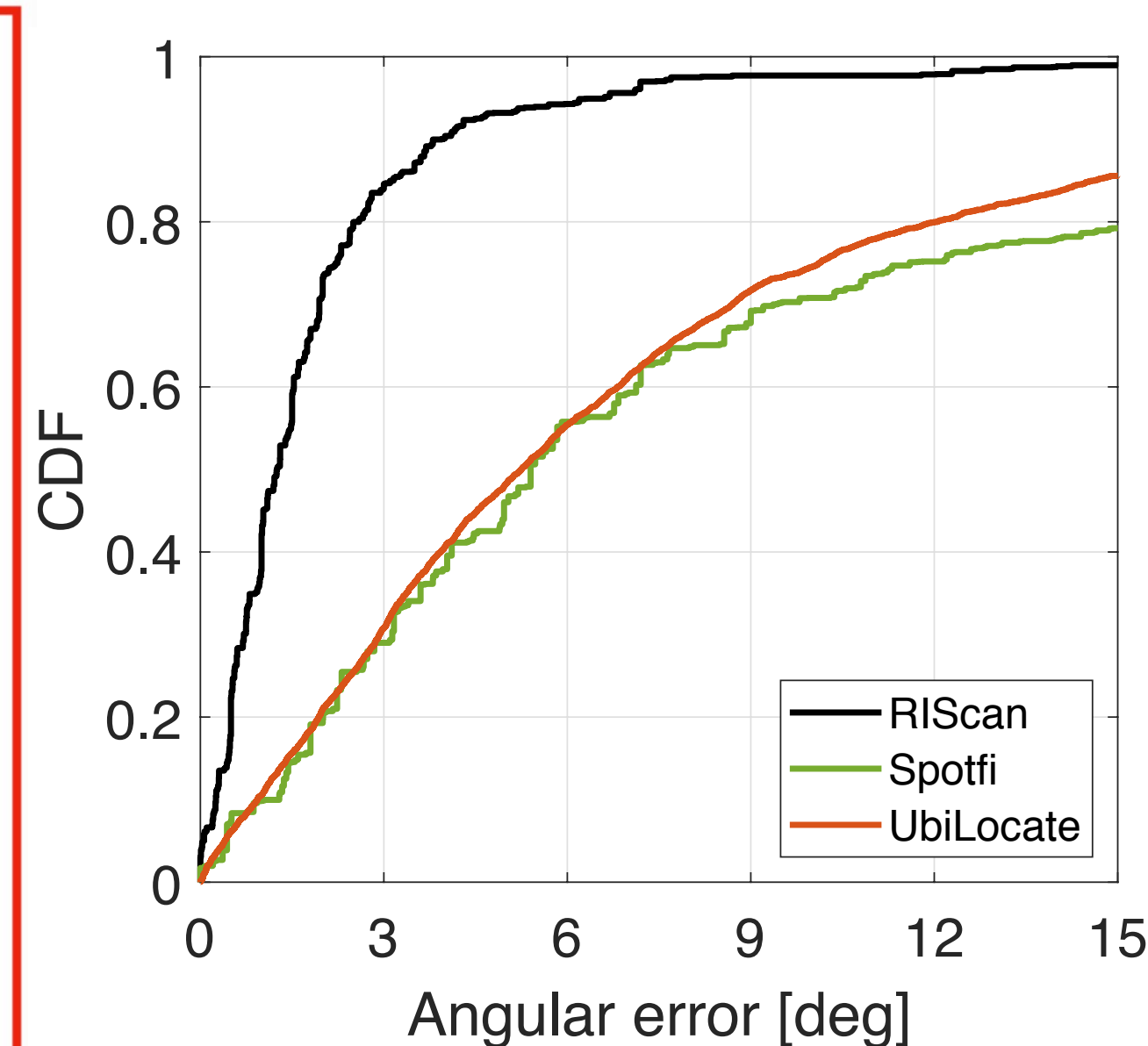
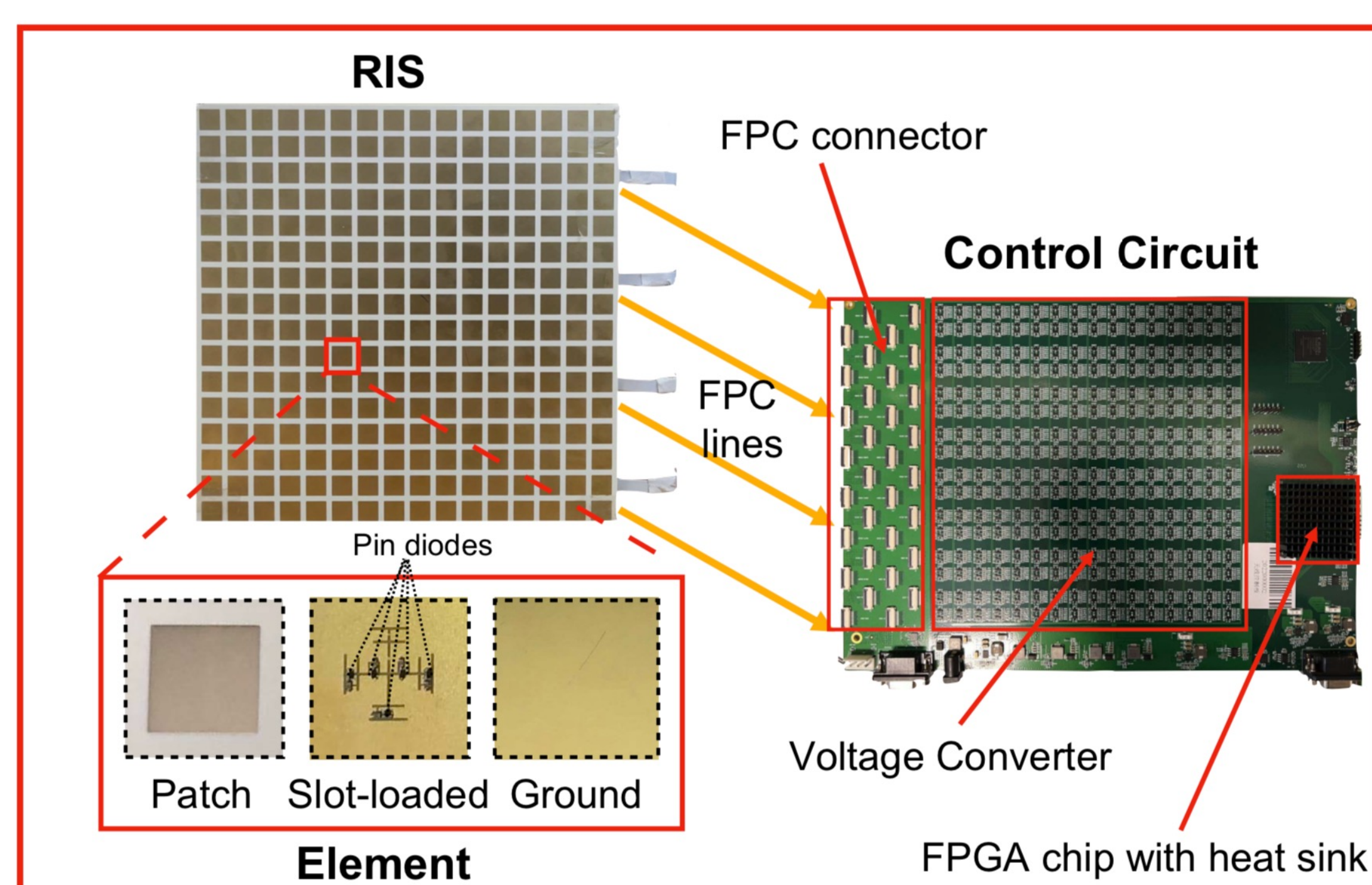
- Leverage RIS to perform **Wi-Fi beam scanning** to let all clients obtain their RIS angle of departure (RAoD) in a single scan simultaneously
- Combine the direction estimation results from two RIS anchors and get the position with **triangulation**



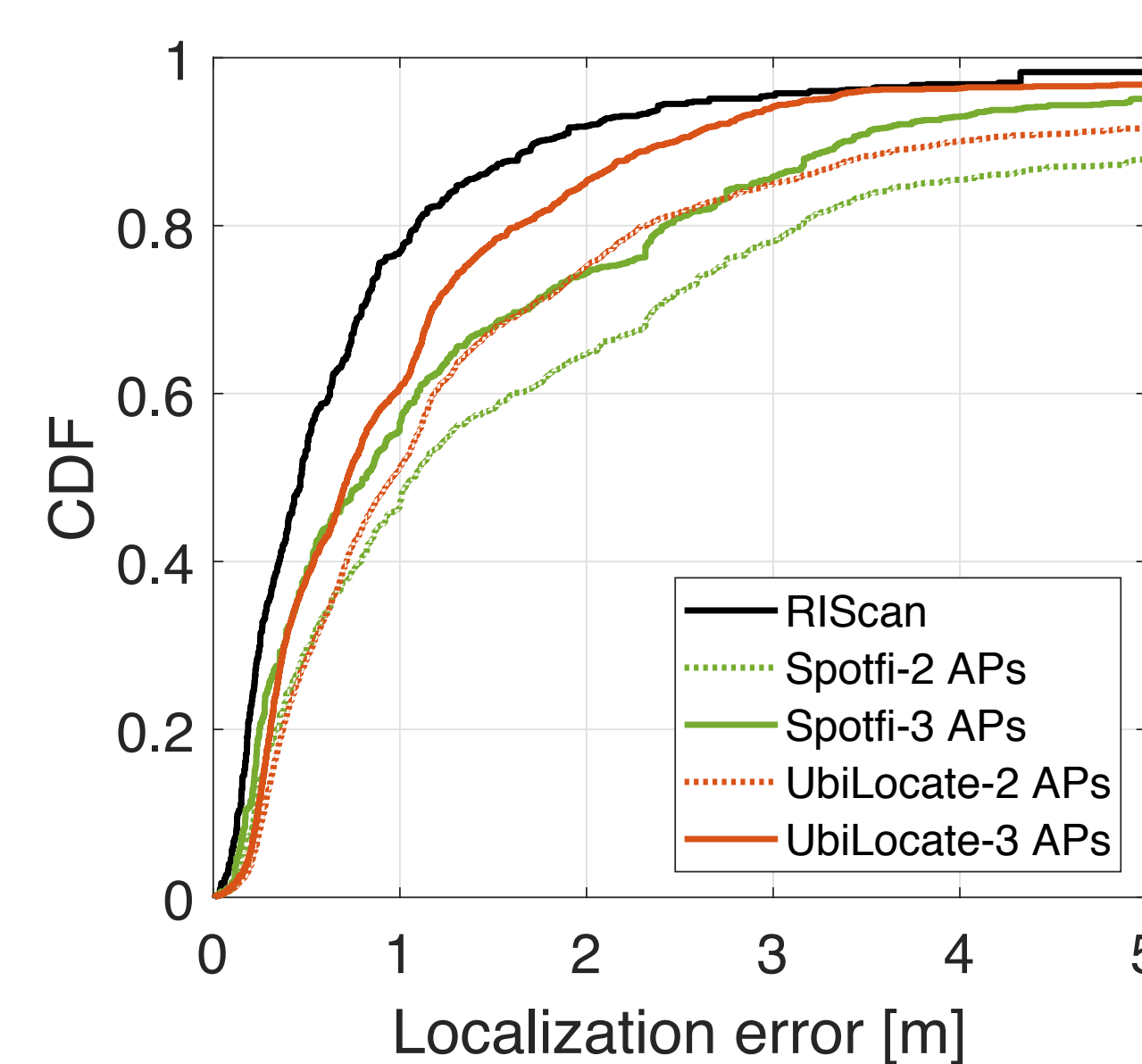
### System Overview and Key Design Highlights



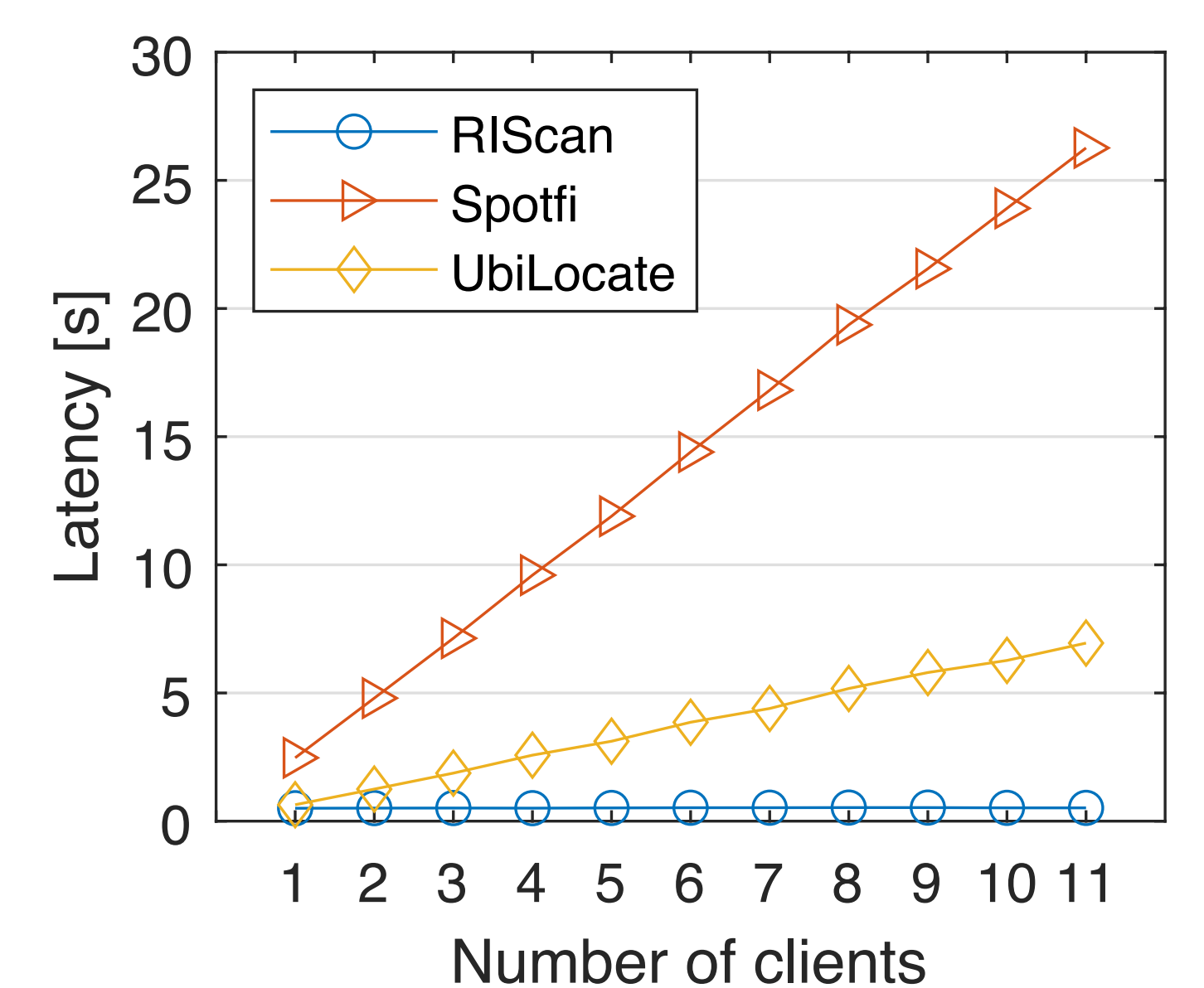
### Implementation and Experimental Results



The median angular error of RIScan is 1.3 degree



The median localization error of RIScan is 47cm



RIScan has the same localization latency of 544ms for each client

### Our Related Publications

Li, C., Huang, Q., Zhou, Y., Huang, Y., Hu, Q., Chen, H., & Zhang, Q. (2023, November). RIScan: RIS-aided Multi-user Indoor Localization Using COTS Wi-Fi. In *Proceedings of the 21st ACM Conference on Embedded Networked Sensor Systems* (pp. 445-458).

### Acknowledgment

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